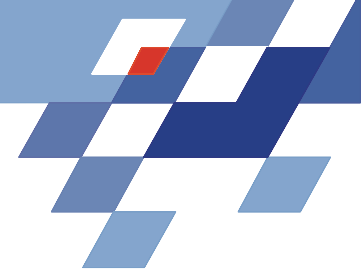


# **HYBRID ALGORITHMS FOR STOCHASTIC INTEGER PROGRAMS IN CHEMICAL BATCH SCHEDULING**

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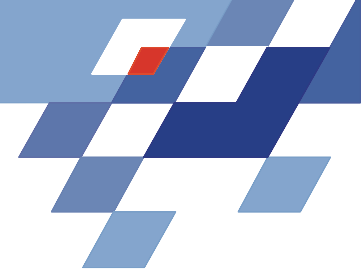




## OUTLINE

- 1. CHEMICAL BATCH SCHEDULING**
- 2. STOCHASTIC INTEGER PROGRAMS**
- 3. HYBRID EVOLUTIONARY ALGORITHMS**
  - ▶ General Evolution Strategy
  - ▶ Specific Evolutionary Algorithm
  - ▶ Comparative Numerical Tests





# CHEMICAL BATCH SCHEDULING

## ▶ GIVEN

- ◆ Flexible multi-product batch plant
- ◆ Recipes for batch-wise production

## ▶ BATCH SCHEDULING

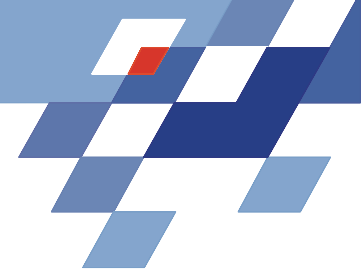
- ◆ Feasible and optimal assignment of processing steps – plant units – time

## ▶ MIXED-INTEGER LINEAR PROGRAM (MILP)

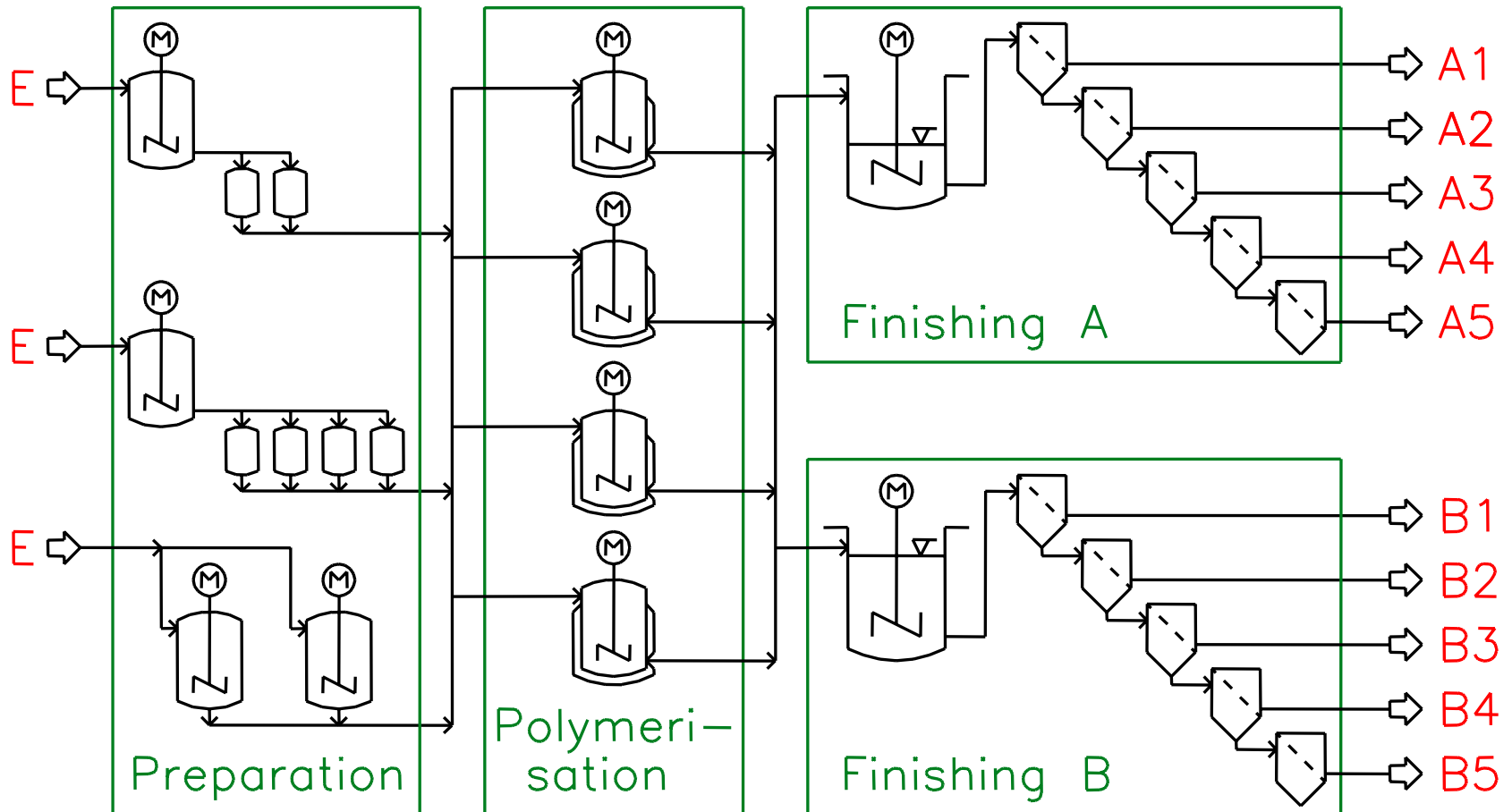
## ▶ REAL-TIME CONDITIONS

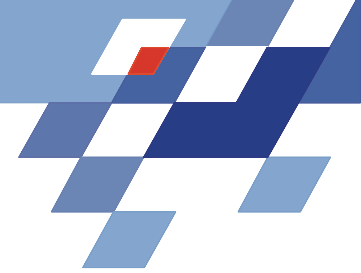
- ◆ Uncertain data: large-scale problems
- ◆ Limited solution time: fast algorithms





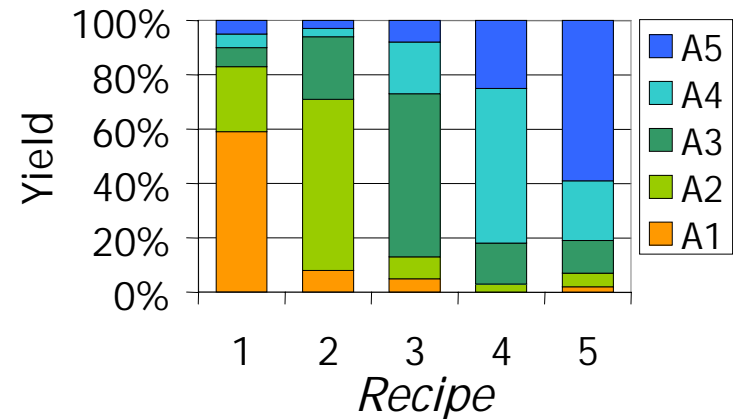
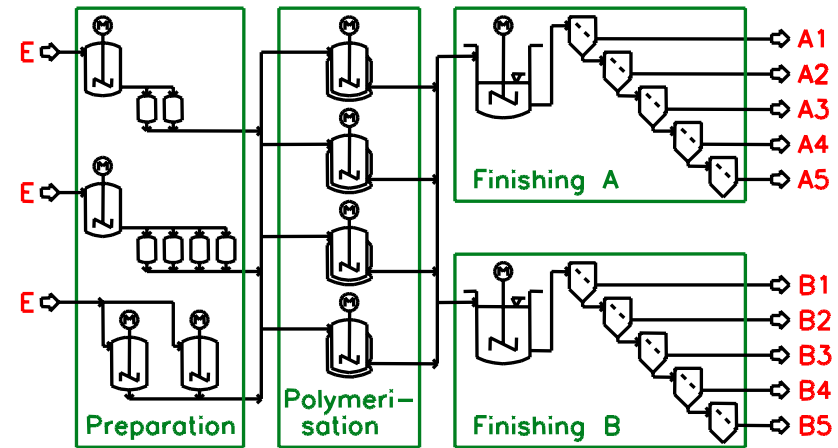
# EPS-PRODUCTION

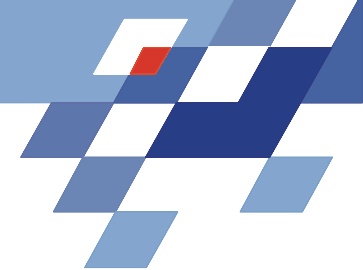




# AGGREGATED SCHEDULING MODEL

- ▶ **MOVING HORIZON**
- ▶ **DISCRETE DECISIONS**
  - ◆ Number, timing and recipes of batches
  - ◆ Operation *Finishing*
- ▶ **CONSTRAINTS**
  - ◆ Capacity *Polymerization*
  - ◆ Capacity *Finishing*
  - ◆ Dynamics *Finishing*
- ▶ **ECONOMIC OBJECTIVE**
- ▶ **UNCERTAINTIES**
  - ◆ Demand
  - ◆ Capacity *Polymerization*

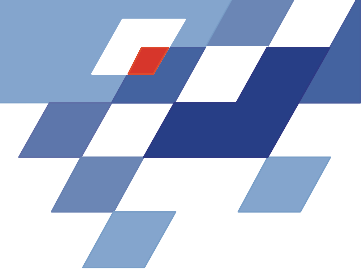




# DETERMINISTIC BASE MODEL

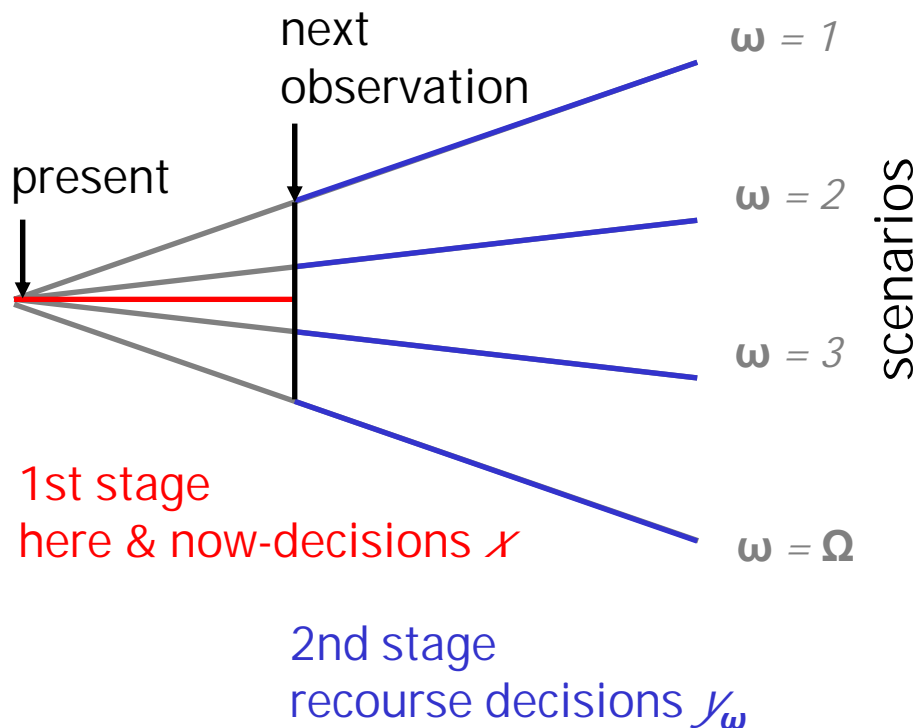
$$\begin{aligned}
 & \max \sum_{p=1}^P \left( \sum_{l=1}^L \sum_{i=1}^l \sum_{f_p=1}^{F_p} \alpha_{lif_p} M_{lif_p} - \sum_{i=1}^l \sum_{f_p=1}^{F_p} \alpha_{if_p}^+ M_{if_p}^+ - \sum_{i=1}^l \sum_{f_p=1}^{F_p} \alpha_{if_p}^- B_{if_p}^- - \sum_{i=1}^l \sum_{r_p=1}^{R_p} \beta_{ir_p} N_{ir_p} - \sum_{i=1}^{l+1} \gamma_{ip} w_{ip} \right) && \text{profit} \\
 & \text{s.t.} \sum_{l=1}^L \begin{cases} M_{l(i+l-1)f_p} & \text{if } i+l-1 \leq l \\ 0 & \text{else} \end{cases} = B_{if_p}^{\text{CUS}} - B_{if_p}^- \quad \forall i, f_p \mid i \leq l && \text{demand} \\
 & \sum_{j=1}^i \sum_{l=1}^L \begin{cases} M_{ljf_p} & \text{if } j \geq l \\ 0 & \text{else} \end{cases} \leq \sum_{j=1}^i \sum_{r_p=1}^{R_p} \bar{\rho}_{f_p r_p} N_{jr_p} \quad \forall i, f_p \mid i \leq l && \text{supply} \\
 & M_{if_p}^+ \geq \sum_{j=1}^i \sum_{r_p=1}^{R_p} \bar{\rho}_{f_p r_p} N_{jr_p} - \sum_{j=1}^i B_{if_p}^{\text{CUS}} \quad \forall i, f_p \mid i \leq l && \text{oversupply} \\
 & w_{ip} \geq \begin{cases} z_p^0 & \text{if } i=1 \\ z_{(i-1)p} & \text{else} \end{cases} - z_{ip} \wedge w_{ip} \geq z_{ip} - \begin{cases} z_p^0 & \text{if } i=1 \\ z_{(i-1)p} & \text{else} \end{cases} \quad \forall i, p && \text{state-change} \\
 & & & \text{finishing lines} \\
 & \sum_{j=i}^k \sum_{p=1}^P \sum_{r_p=1}^{R_p} N_{jr_p} \leq N_{ik}^{\max} \quad \forall i, k \mid i \leq k \leq l && \text{capacity} \\
 & & & \text{polymerization} \\
 & \sum_{j=i}^k \sum_{r_p=1}^{R_p} N_{jr_p} \leq v_{kp} C_p^{\max} - \begin{cases} C_p^0 & \text{if } i=1 \\ v_{(i-1)p} C_p^{\min} & \text{else} \end{cases} + \sum_{j=i}^k z_{jp} F_p^{\max} \quad \forall i, k, p \mid i \leq k \leq l && \text{max capacity} \\
 & & & \text{finishing lines} \\
 & \sum_{j=i}^k \sum_{r_p=1}^{R_p} N_{jr_p} \geq v_{kp} C_p^{\min} - \begin{cases} C_p^0 & \text{if } i=1 \\ v_{(i-1)p} C_p^{\max} & \text{else} \end{cases} + \sum_{j=i}^k z_{jp} F_p^{\min} \quad \forall i, k, p \mid i \leq k \leq l && \text{min. capacity} \\
 & & & \text{finishing lines} \\
 & v_{ip} \leq z_{ip} \wedge v_{ip} \leq z_{(i+1)p} \wedge v_{ip} \geq z_{ip} + z_{(i+1)p} - 1 \quad \forall i, p \mid i \leq l \\
 & z_{ip} \in \{0,1\}, \quad N_{ir_p} \in \mathbb{N}, \quad M_{lif_p}, M_{if_p}^+, B_{if_p}^-, w_{ip}, v_{ip} \in \mathbb{R}_+
 \end{aligned}$$





# STOCHASTIC INTEGER PROGRAMS

## ▶ INFORMATION- AND DECISION STRUCTURE



## ▶ DETERMINISTIC EQUIVALENT

$$\min_{x, y_\omega} \quad c^T x + \sum_{\omega=1}^{\Omega} \pi_\omega q_\omega^T y_\omega$$

$$\text{s.t.} \quad Ax \leq b,$$

$$T_\omega x + W_\omega y_\omega \leq h_\omega,$$

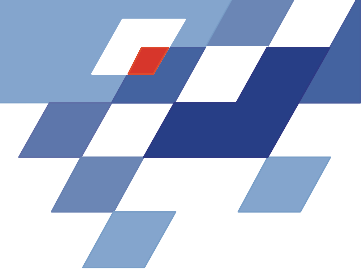
$$x \in X, y_\omega \in Y, \omega = \{1, \dots, \Omega\},$$

$$X, Y \in \mathbb{R} \times \mathbb{N}.$$

## ▶ MATRIX STRUCTURE

$$\begin{bmatrix} \boxed{A} & 0 & 0 & 0 \\ \boxed{T_1} & \boxed{W_1} & 0 & 0 \\ \vdots & 0 & \ddots & 0 \\ \boxed{T_\Omega} & 0 & 0 & \boxed{W_\Omega} \end{bmatrix} \begin{pmatrix} x \\ y_1 \\ \vdots \\ y_\Omega \end{pmatrix} \leq \begin{pmatrix} b \\ h_1 \\ \vdots \\ h_\Omega \end{pmatrix}$$

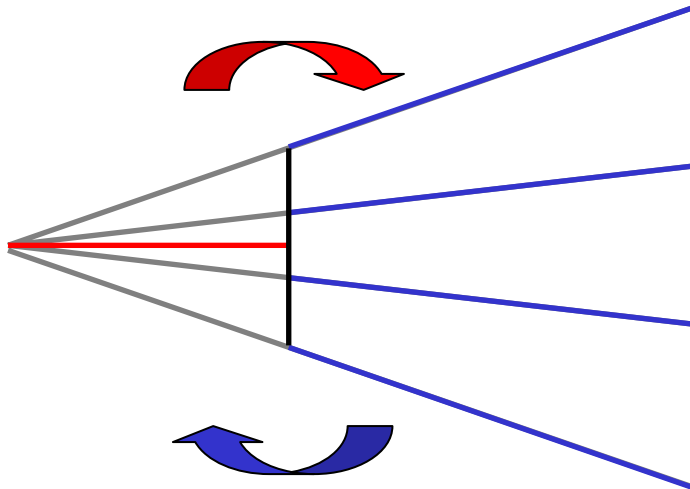




# STAGE DECOMPOSITION

## ► HYBRID ALGORITHM

*Evolutionary algorithm:  
solution candidates  $x$*



*MILP-algorithm (CPLEX):  
Objective value (fitness)*

*Masterproblem: 1st stage*

$$\begin{aligned} \min_x \quad & c^T x + \sum_{\omega=1}^{\Omega} \pi_{\omega} Q_{\omega}(x) \\ \text{s.t.} \quad & Ax \leq b, x \in X \end{aligned}$$

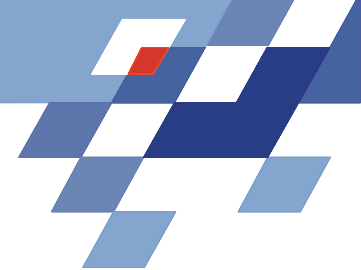
*Subproblems: 2nd stage*

$$\begin{aligned} Q_{\omega}(x) = \min_{y_{\omega}} \quad & q_{\omega}^T y_{\omega} \\ \text{s.t.} \quad & W_{\omega} y_{\omega} \leq h_{\omega} - T_{\omega} x, \\ & y_{\omega} \in Y \end{aligned}$$

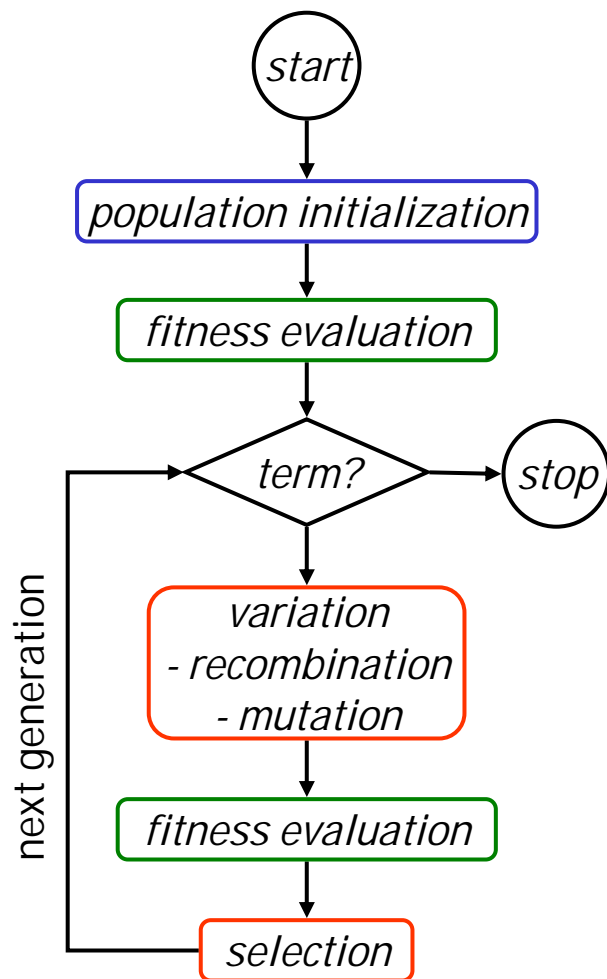
- ◆ non-convex in  $x$
- ◆ not necessarily feasible (no relative complete recourse)





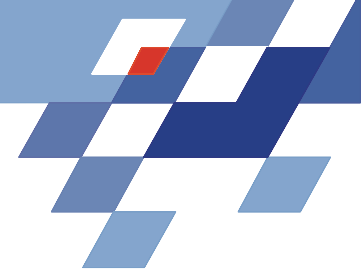


# EVOLUTIONARY ALGORITHMS

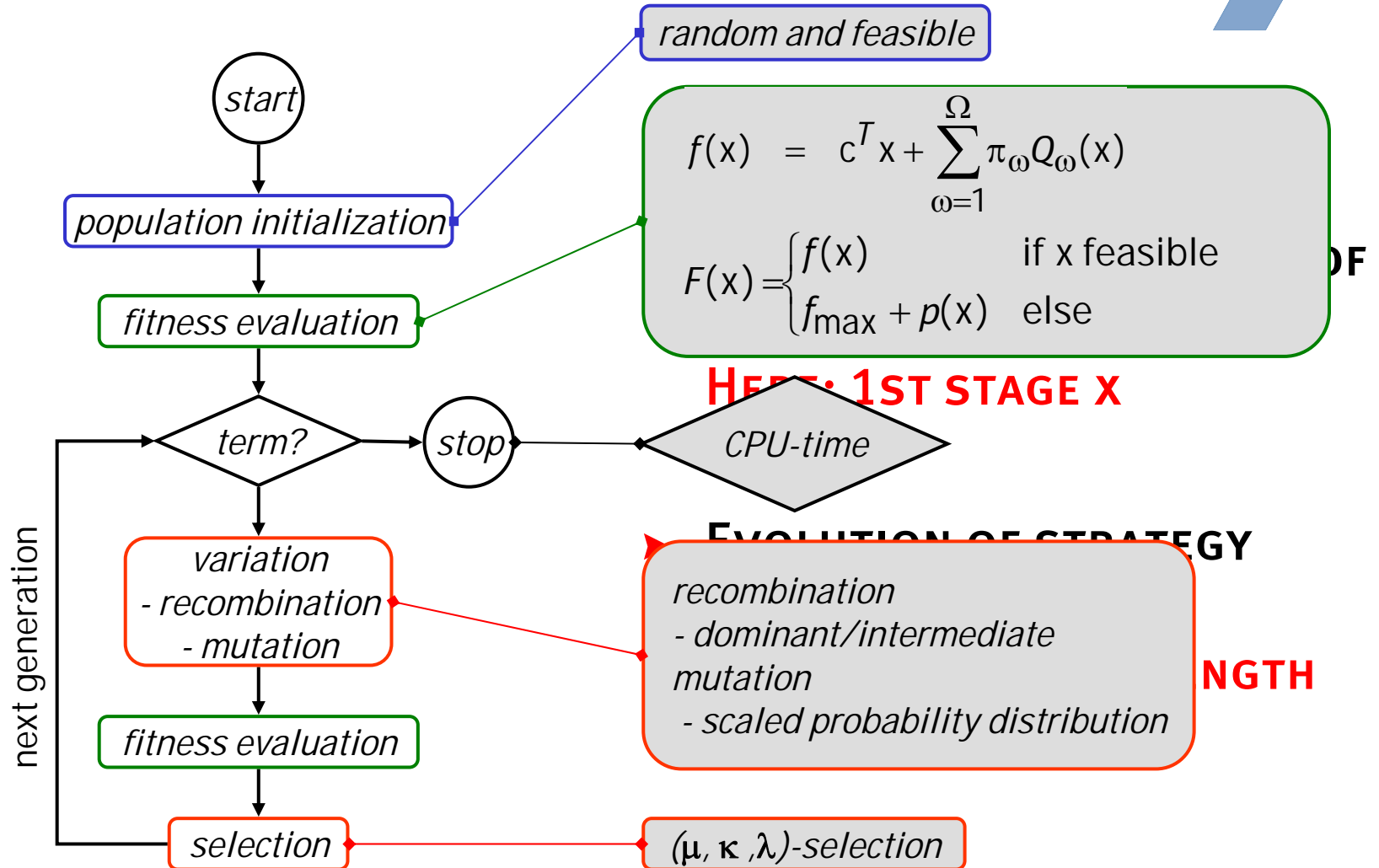


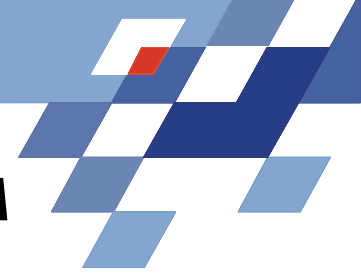
- ▶ **IMITATE NATURAL EVOLUTION**  
“*SURVIVAL OF THE FITTEST*”
- ▶ **RANDOMIZED SEARCH**
- ▶ **POPULATION OF INDIVIDUALS**
- ▶ **BLACK-BOX FITNESS FUNCTION**
- ▶ **VARIATION-SELECTION-PARADIGM**
  - ◆ Variation: diversity
  - ◆ Selection: direction
- ▶ **THEORETICAL PROPERTIES**
  - ◆ No optimality bounds
  - ◆ No convergence guarantee
- ▶ **CLASSES**
  - ◆ Genetic algorithms
  - ◆ Evolution strategies ...



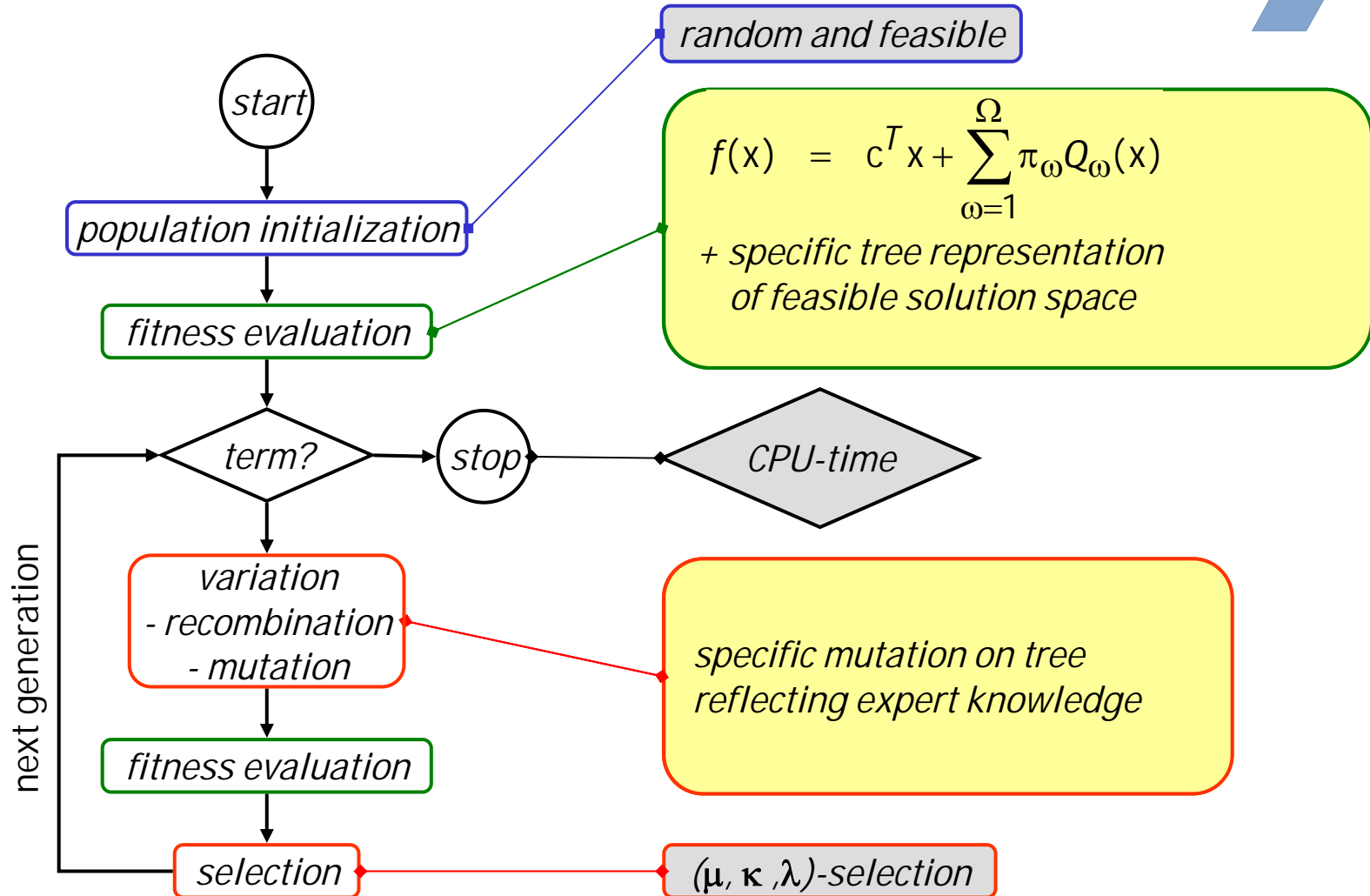


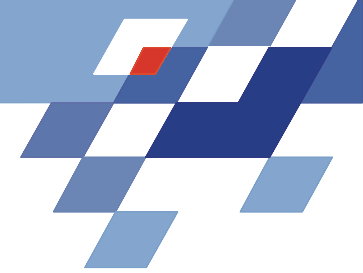
# 1. GENERAL EVOLUTION STRATEGY





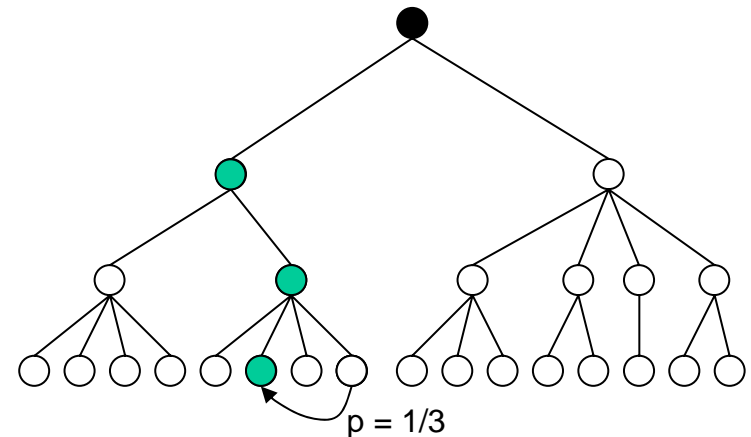
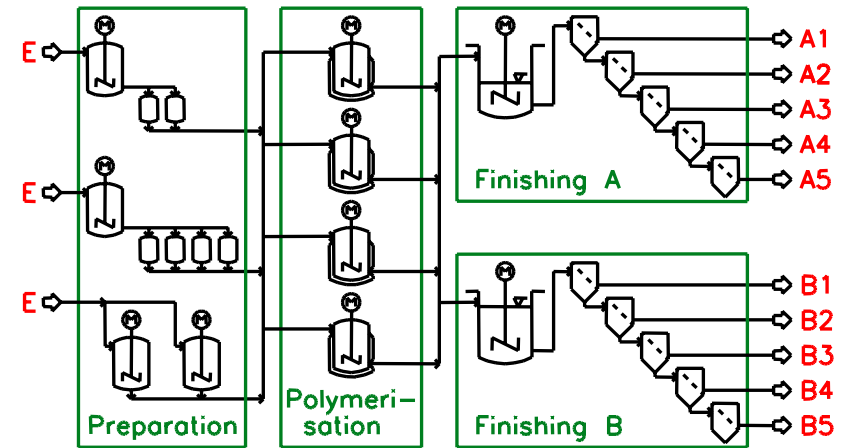
## 2. SPECIFIC EVOLUTIONARY ALGORITHM

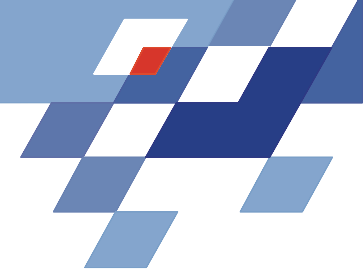




# SPECIFIC TREE REPRESENTATION

- ▶ **DECISION TREE OF FEASIBLE SOLUTIONS**
- ▶ **STRONG HIERARCHY OF DECISIONS**
  1. Operation *Finishing*
  2. Feed *Finishing*
  3. Number, timing and recipes of batches
- ▶ **DYNAMIC GENERATION FROM SMALL SET OF SUB-TREES**





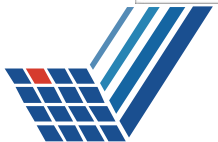
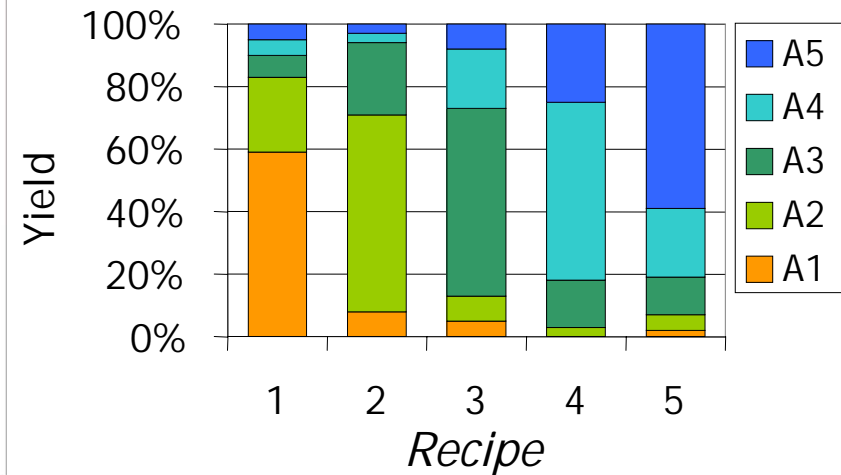
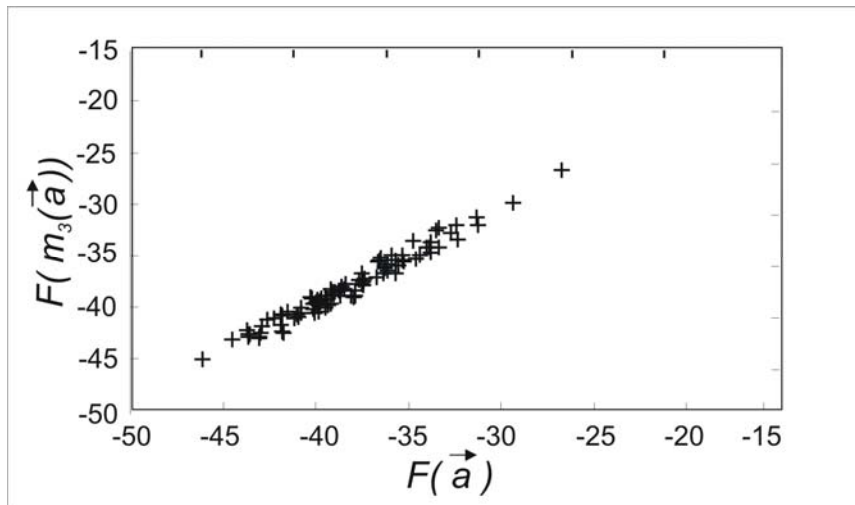
# SPECIFIC MUTATION OPERATORS

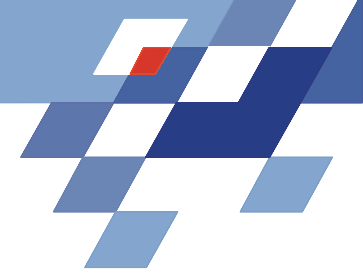
## ► DESIGN CRITERIA

- ◆ Reachability
- ◆ Unbiasdness
- ◆ Scalability
- ◆ Causality

## ► EXPERT KNOWLEDGE

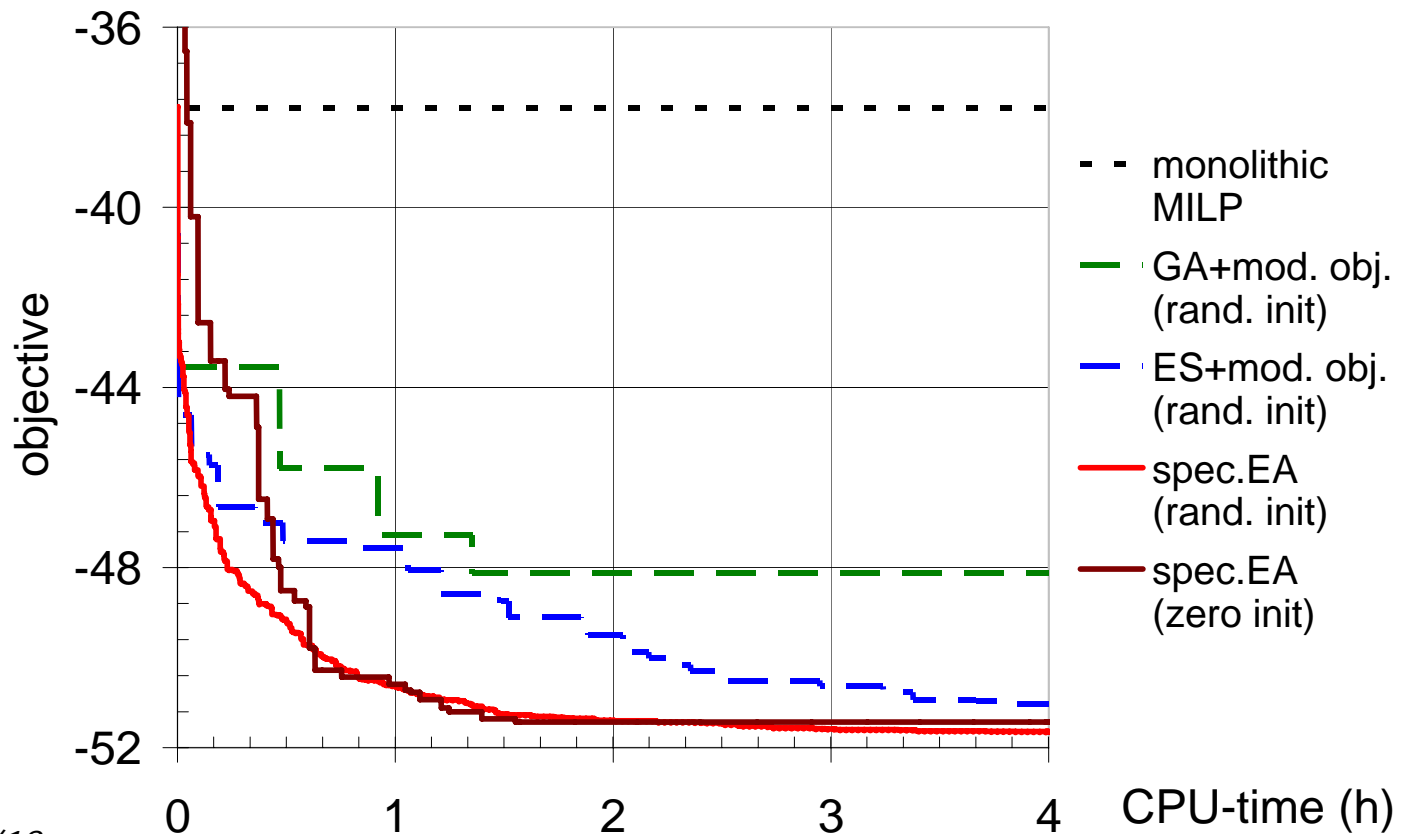
- ◆ Similarity of recipes
- ◆ Temporal order

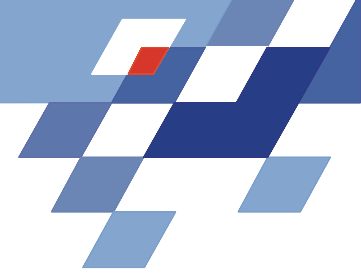




# HYBRID ALGORITHMS

- ▶ 16 DEMAND SCENARIOS
- ▶ 3 FIRST STAGE INTERVALS
- ▶ 4 SECOND STAGE INTERVALS
- ▶ 1,568 DISCRETE VARIABLES
- ▶ 5,601 CONTINUOUS VARIABLES
- ▶ 4,083 CONSTRAINTS

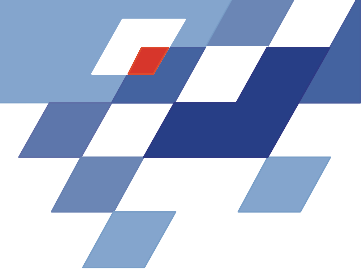




## DUAL/SCENARIO DECOMPOSITION

- ▶ **BRANCH & BOUND-ALGORITHM (CARØE & SCHULTZ)**
  1. *Initialization*: Set  $Z^* := \infty$  (best current solution) and let  $P$  (list of untreated problems) consist of the original problem.
  2. *Termination*: If  $P = \emptyset$  then  $Z^*$  is optimal.
  3. *Node Selection*: Select and delete a problem  $P \in P$  and solve its **Lagrangian Dual**. If  $P$  is infeasible, set  $Z^{\text{LD}} := \infty$ . If  $Z^{\text{LD}}(P) \geq Z^*$  go to 2.
  4. *Bounding*: Determine **heuristically** a solution suggestion  $x^{\text{R}}$ . If  $Z^{\text{R}} < Z^*$  set  $Z^* := Z^{\text{R}}$  and delete all  $P' \in P$  with  $Z^{\text{LD}}(P') \geq Z^*$ .
  5. *Branching*: Select a component  $x_{(k)}$  and add two new problems to  $P$  by extending  $P$  by the additional constraints  $x_{(k)} \leq x_{(k)}^{\text{R}}$  and  $x_{(k)} > x_{(k)}^{\text{R}}$ . Go to 3.

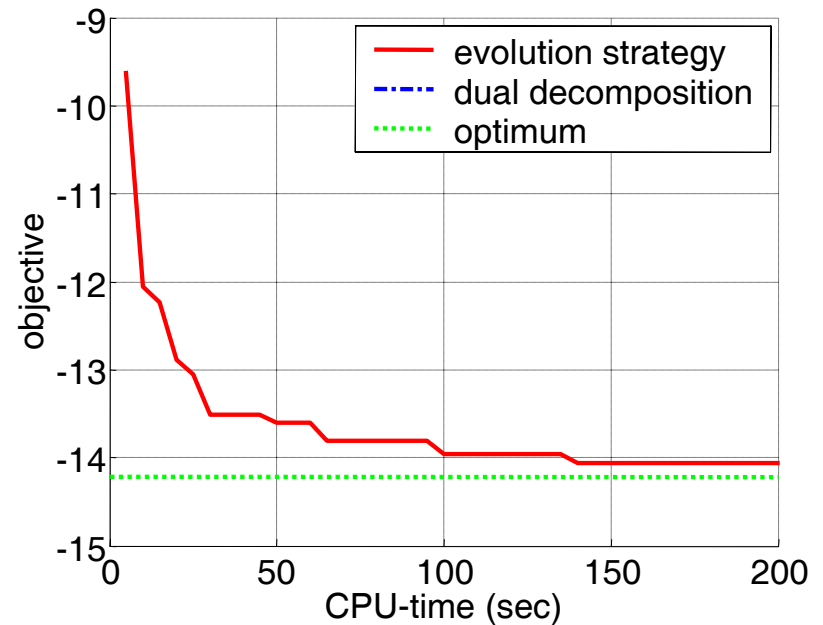
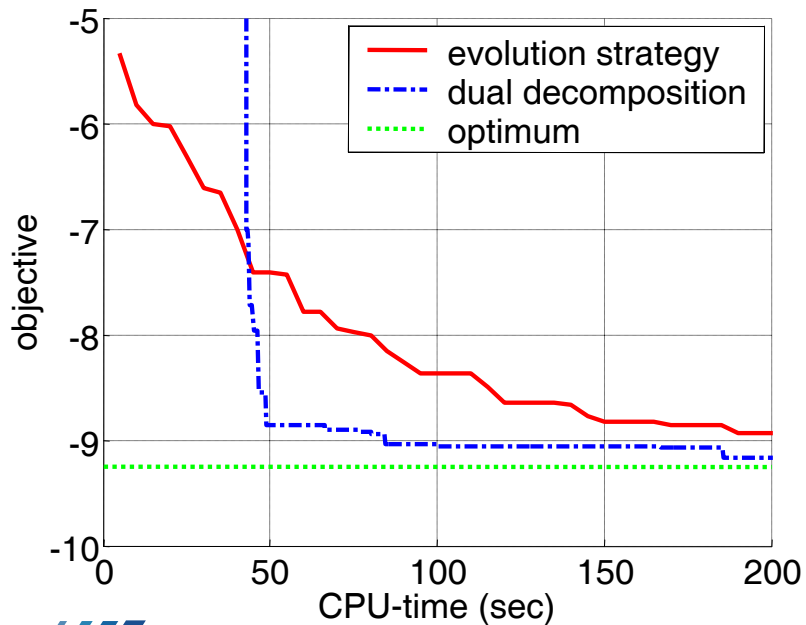




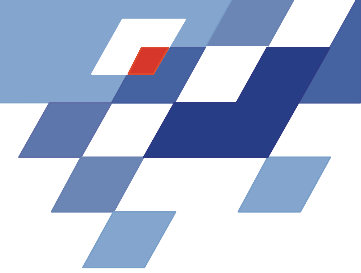
# RIGOROUS VS. STOCHASTIC ALGORITHM

- ▶ UNCERTAIN DEMANDS
- ▶ **RELATIVE COMPLETE RECOURSE**
- ▶ 1,144 VARIABLES
- ▶ 716 CONSTRAINTS

- ▶ UNCERTAIN DEMANDS & CAPACITY
- ▶ **NO RELATIVE COMPLETE RECOURSE**
- ▶ 1,256 VARIABLES
- ▶ 842 CONSTRAINTS



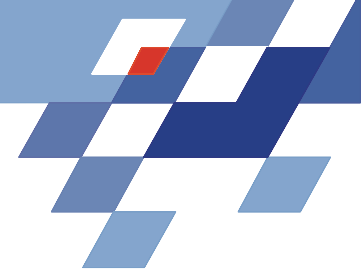




## ESSENCE

- ▶ **CHEMICAL BATCH SCHEDULING PROBLEMS AS  
2-STAGE STOCHASTIC INTEGER PROGRAMS**
- ▶ **FAST SOLUTION BY  
STRUCTURAL SPECIFIC HYBRID ALGORITHMS**
- ▶ **ACCELERATION BY SYSTEMATIC  
INTEGRATION OF EXPERT KNOWLEDGE**





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